Yes, let's take a byte out of this apple

(I am sorry I am dad and grandfather and I live for these puns.

This presentation is partially based on the podcasts by Mitch Davis - Bare-Metal MCU

### Why? Speed and Efficiency



#### The Bootloader

The behaviour described above happens thanks to a special piece of code that is executed at every reset of the microcontroller and that looks for a sketch to be uploaded from the serial/USB port using a specific protocol and speed. If no connection is detected, the execution is passed to the code of your sketch.

This little (usually 512 bytes) piece of code is called the "Bootloader" and it is in an area of the memory of the microcontroller – at the end of the address space - that can't be reprogrammed as a regular sketch and had been designed for such purpose.



The Memory Map of an ATmega328P

When we mentioned Arduino Bootloader earlier in the class, we spoke about memory.

Specific memory blocks are called registers



The Memory Map of an ATmega328P

Registers are memory blocks containing essential data for controlling or setting up microcontrollers.



Each port is controlled by three registers, which are also defined variables in the arduino language. The DDR register, determines whether the pin is an INPUT or OUTPUT. The PORT register controls whether the pin is HIGH or LOW, and the PIN register reads the state of INPUT pins set to input with pinMode().

Registers are memory blocks containing essential data for controlling or setting up microcontrollers.



Each port is controlled by three registers, which are also defined variables in the arduino language. The DDR register, determines whether the pin is an INPUT or OUTPUT. The PORT register controls whether the pin is HIGH or LOW, and the PIN register reads the state of INPUT pins set to input with pinMode().



Each port is controlled by three registers, which are also defined variables in the arduino language. The DDR register, determines whether the pin is an INPUT or OUTPUT. The PORT register controls whether the pin is HIGH or **LOW**, and the PIN register reads the state of INPUT pins set to input with pinMode().

Ok, but what is a register exactly?



Each port is controlled by three registers, which are also defined variables in the arduino language. The DDR register, determines whether the pin is an INPUT or OUTPUT. The PORT register controls whether the pin is HIGH or LOW, and the **PIN register** reads the state of INPUT pins set to input with pinMode().

Registers are memory blocks containing essential data for controlling or setting up microcontrollers.

```
void setup() {
    // initialize the LED pin as an output:
    pinMode(ledPin, OUTPUT); DDR Responsibility
    // initialize the pushbutton pin as an input:
    pinMode(buttonPin,INPUT_PULLUP); DDR Responsibility
    }
```

```
void loop() {
    // read the state of the pushbutton value:
    buttonState = digitalRead(buttonPin);
```

```
\ensuremath{//} check if the pushbutton is pressed. If it is, the buttonState is HIGH:
```

```
if (buttonState == HIGH) {
   // turn LED on:
   digitalWrite(ledPin, HIGH);
} else {
   // turn LED off:
   digitalWrite(ledDim___LOW);
```

```
digitalWrite(ledPin, LOW);
```

} }

Each port is controlled by three registers, which are also defined variables in the arduino language. The DDR register, determines whether the pin is an INPUT or OUTPUT. The PORT register controls whether the pin is HIGH or LOW, and the PIN register reads the state of INPUT pins set to input with pinMode().

### Look at our Arduino code to use a momentary switch with a LED.

```
void setup() {
  // initialize the LED pin as an output:
  pinMode(ledPin, OUTPUT);
  // initialize the pushbutton pin as an input:
  pinMode(buttonPin,INPUT_PULLUP);
void loop() {
  // read the state of the pushbutton value:
  buttonState = digitalRead(buttonPin):
  // check if the pushbutton is pressed. If it is, the
buttonState is HTGH:
  if (buttonState == HIGH) {
   // turn LED on:
    digitalWrite(ledPin, HIGH); Port Responsibility
  } else {
    // turn LED off:
    digitalWrite(ledPin, LOW); Port Responsibility
```

Each port is controlled by three registers, which are also defined variables in the arduino language. The DDR register, determines whether the pin is an INPUT or OUTPUT. The **PORT** register controls whether the pin is HIGH or **LOW**, and the PIN register reads the state of INPUT pins set to input with pinMode().

Look at our Arduino code to use a momentary switch with a LED.

```
void setup() {
    // initialize the LED pin as an output:
    pinMode(ledPin, OUTPUT);
    // initialize the pushbutton pin as an input:
    pinMode(buttonPin,INPUT_PULLUP);
    }
```

```
void loop() {
    // read the state of the pushbutton value:
    buttonState = digitalRead(buttonPin); Pin Responsibility
```

```
// check if the pushbutton is pressed. If it is, the
buttonState is HIGH:
```

```
if (buttonState == HIGH) Pin Responsibility
{
    // turn LED on: digitalWrite(ledPin, HIGH);
} else {
    // turn LED off:
    digitalWrite(ledPin, LOW);
```

} } Each port is controlled by three registers, which are also defined variables in the arduino language. The DDR register, determines whether the pin is an INPUT or OUTPUT. The PORT register controls whether the pin is HIGH or LOW, and the **PIN** register reads the state of INPUT pins set to input with pinMode().

Look at our Arduino code to use a momentary switch with a LED.



**Representation of a Binary Number** 

١	MSB			Bi	inary Dig	git			LSB
	2 <sup>8</sup>	27	2 <sup>6</sup>	2 <sup>5</sup>	24	2 <sup>3</sup>	2 <sup>2</sup>	21	2 <sup>0</sup>
	256	128	64	32	16	8	4	2	1

We saw above that in the decimal number system, the weight of each digit from right to left increases by a factor of 10. In the binary number system, the weight of each digit increases by a factor of 2 as shown. Then the first digit has a weight of  $1(2^0)$ , the second digit has a weight of  $2(2^1)$ , the third a weight of  $4(2^2)$ , the fourth a weight of  $8(2^3)$  and so on.

So for example, converting a **Binary to Decimal** number would be:

Decimal Digit Value	256	128	64	32	16	8	4	2	1
Binary Digit Value	1	0	1	1	0	0	1	0	1

By adding together ALL the decimal number values from right to left at the positions that are represented by a "1" gives us:  $(256) + (64) + (32) + (4) + (1) = 357_{10}$  or three hundred and fifty seven as a decimal number.

Please note: The Arduino Port Registers are 8 bit.

0	0	1	1	0	0	1	0
0	0	32	16	0	0	2	0

50 = 0+0+32+16+0+02+0

The decimal equivalent of 00110010 is 50

Please note: The Arduino Port Registers are 8 bit.

Convert 00100010 to decimal

0	0	1	0	0	0	1	0

What is the decimal equivalent?

Please note: The Arduino Port Registers are 8 bit.

Convert 00100010 to decimal

0	0	1	0	0	0	1	0
0	0	<mark>32</mark>	0	0	0	<mark>2</mark>	0

What is the decimal equivalent?  $34 = \frac{32}{2} + \frac{2}{2}$ 



# Port Register How to:



Let's return back to the Arduino. PLease review how we would program the BuiltIn LED pin (13) to blink using Arduino code.



Want to see it work? Please access Circuit in TinkerCad. Select an Arduino and review how to program Pin 13 or the BuiltIn Pin See <u>link</u>

```
// C++ code
```

```
void setup()
```

```
{
```

pinMode(LED\_BUILTIN, OUTPUT);

```
}
```

```
void loop()
```

```
{
```

digitalWrite(LED\_BUILTIN, HIGH); delay(1000); // Wait for 1000 millisecond(s) digitalWrite(LED\_BUILTIN, LOW); delay(1000); // Wait for 1000 millisecond(s)

#### Port B has an 8 Bit Register

PortB	Digital	Pin 8
-------	---------	-------

- PortB<mark>1</mark> Digital Pin 9
- PortB<sup>2</sup> Digital Pin 10
- PortB<mark>3</mark> Digital Pin 11
- PortB<mark>4</mark> Digital Pin 12
- PortB Digital Pin 13 (LED\_BUILTIN);
- We cannot access PortB<mark>6</mark> or PORTB
- We want to turn on Pin13

Therefore all the ports are set to Zero except for PortB5

00100000 binary

00320000 = 0+0+32+0+0+0+0

Port	Bin	Dec
B0	0	0
B1	0	0
B2	0	0
B3	0	0
B4	0	0
<mark>B5</mark>	1	<mark>32</mark>
B6	0	0
B7	0	0



Now use the decimal equivalent to turn on BUILTIN LED

HINT 32

Click <u>here</u> for solution



### Click <u>here</u> for solution

Now use turn on digital **pin 9** using the PORT variable to turn on a LED.

## HINT: You will need a breadboard, resistor and LED



# DDR Register How to:



Click <u>here</u> for solution

void setup()

```
{
```

//pinMode(LED\_BUILTIN, OUTPUT);

DDRB = 32;// B010000 sets PB5 as OUTPUT PB5 is 0010000 or 32

```
void loop()
```

```
{
```

PORTB=32; //0010000;

delay(2000); // Wait for 1000 millisecond(s)

```
PORTB=0;
```

delay(1000); // Wait for 1000 millisecond(s)

```
}
```



Now go ahead and change the DDR register variable to suit Pin 9



#### 14.4.2 PORTB - The Port B Data Register

Bit	7	6	5	4	3	2	1	0	_
0x05 (0x25)	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	PORTB
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.3 DDRB - The Port B Data Direction Register

Bit	7	6	5	4	3	2	1	0	_
0x04 (0x24)	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	DDRB
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.4 PINB - The Port B Input Pins Address<sup>(1)</sup>

Bit	7	6	5	4	3	2	1	0	_
0x03 (0x23)	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	PINB
Read/Write	R/W								
Initial Value	N/A								



#### 14.4.2 PORTB - The Port B Data Register

Bit	7	6	5	4	3	2	1	0	_
0x05 (0x25)	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	PORTB
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.3 DDRB - The Port B Data Direction Register

Bit	7	6	5	4	3	2	1	0	_
0x04 (0x24)	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	DDRB
Read/Write	R/W	-							
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.4 PINB - The Port B Input Pins Address<sup>(1)</sup>

Bit	7	6	5	4	3	2	1	0	_
0x03 (0x23)	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	PINB
Read/Write	R/W								
Initial Value	N/A								

So how do we write 32 to 0x25 (PORTB)?

#### 14.4.2 PORTB - The Port B Data Register

Bit	7	6	5	4	3	2	1	0	
0x05 (0x25)	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	PORTB
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.3 DDRB - The Port B Data Direction Register

Bit	7	6	5	4	3	2	1	0	
0x04 (0x24)	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	DDRB
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.4 PINB – The Port B Input Pins Address<sup>(1)</sup>

Bit	7	6	5	4	3	2	1	0	_
0x03 (0x23)	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	PINB
Read/Write	R/W								
Initial Value	N/A								

So how do we write 32 to 0x25 (PORTB)?

We use **pointers**!

#### 14.4.2 PORTB - The Port B Data Register

Bit	7	6	5	4	3	2	1	0	_
0x05 (0x25)	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	PORTB
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.3 DDRB - The Port B Data Direction Register

Bit	7	6	5	4	3	2	1	0	
0x04 (0x24)	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	DDRB
Read/Write	R/W	-							
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.4 PINB - The Port B Input Pins Address<sup>(1)</sup>

Bit	7	6	5	4	3	2	1	0	
0x03 (0x23)	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	PINB
Read/Write	R/W								
Initial Value	N/A								

So how do we write 32 to Ox25 (PORTB)?

### We use **pointers**!

A **Pointer** in the C language is a variable that **points** to the memory location of another variable memory address.

#### 14.4.2 PORTB - The Port B Data Register

Bit	7	6	5	4	3	2	1	0	
0x05 (0x25)	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	PORTB
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.3 DDRB - The Port B Data Direction Register

Bit	7	6	5	4	3	2	1	0	
0x04 (0x24)	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	DDRB
Read/Write	R/W								
Initial Value	0	0	0	0	0	0	0	0	

#### 14.4.4 PINB - The Port B Input Pins Address<sup>(1)</sup>

Bit	7	6	5	4	3	2	1	0	_
0x03 (0x23)	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	PINB
 Read/Write	R/W								
Initial Value	N/A								

We use **pointers**!

A **Pointer** in the C language is a variable that **points** to the memory location of another variable memory address.

### Simple Example

int classicVariable = 16; // create a "classic integer variable

int\* pointerToClassicVariable = & classicVariable; //create a pointer to "point" to classicVariable or reference the variable

\* **pointerToClassicVariable = 32**; //dereference pointerToClassicVariable and assign 32 to classicVariable

We use **pointers**!

A **Pointer** in the C language is a variable that **points** to the memory location of another variable memory address.

### So how do we write 32 to 0x25 (PORTB)?

volatile byte\* pointerToRegisterB = 0x25; // create a pointer variable called pointerToRegisterB which is pointed to Ox25; \* pointerToRegisterB = 32; //dereference pointerToRegisterB and assign 32 to memory location to Ox25

### So how do we write 32 to 0x25 (PORTB)?

```
void setup()
```

```
{
DDRB = 32;// B010000 sets PB5 as OUTPUT PB5 is 0010000 or 32 );
}
void loop()
```

```
volatile byte* pointerToRegisterB = 0x25;
*pointerToRegisterB = 32; //PORTB=32;// PORTB is from pinout 32 decimal
```

```
delay(2000); // Wait for 1000 millisecond(s)
```

```
*pointerToRegisterB = 0; //PORTB=0; //PORTB 0 decimal
```

```
delay(1000); // Wait for 1000 millisecond(s)
```

volatile byte\* pointerToRegisterB = 0x25; // create a pointer variable called pointerToRegisterB which is pointed to 0x25;

\* **pointerToRegisterB = 32**; //dereference pointerToRegisterB and assign 32 to memory location to Ox25

### Wow, can we do this all on one line? I don't type well

volatile byte\* pointerToRegisterB = 0x25; // create a pointer variable called pointerToRegisterB which is pointed to Ox25;

\* **pointerToRegisterB = 32**; //dereference pointerToRegisterB and assign 32 to memory location to Ox25

Wow, can we do this all on one line? I don't type well Well, yes we can

Ok, I guess if you say so.

volatile byte\* pointerToRegisterB = 0x25; // create a pointer variable called pointerToRegisterB which is pointed to Ox25;

\* pointerToRegisterB = 32; //dereference pointerToRegisterB and assign 32 to memory location to Ox25

### We can so let me show you.

### \* ( (volatile byte\*) 0x25) = 32;

We assign the memory address 0x25 to a pointer

volatile byte\* pointerToRegisterB = 0x25; // create a pointer variable called pointerToRegisterB which is pointed to Ox25;

\* pointerToRegisterB = 32; //dereference pointerToRegisterB and assign 32 to memory location to Ox25

#### We can say so. Let me show you.

### \* ( (volatile byte\*) 0x25) = 32;

We dereference it with \* and assign the 0x25 to 32

volatile byte\* pointerToRegisterB = 0x25; // create a pointer variable called pointerToRegisterB which is pointed to Ox25;

\* pointerToRegisterB = 32; //dereference pointerToRegisterB and assign 32 to memory location to Ox25

#### We can say so. Let me show you.

### \* ( (volatile byte\*) 0x25) = 32;

We dereference it with \* and assign the 0x25 to 32

### So how do we write 32 to 0x25 (PORTB)?

### yoid loop()

/\* volatile byte\* memoryPointer = (volatile byte\*) 0x25;// we are assigning 0x25 memory to memoryPointer \*memoryPointer=32; \*/

- \* ( (volatile byte\*) 0x25) = 32; //replaces two lines of the above code delay(2000); // Wait for 1000 millisecond(s)
- \* ( (volatile byte\*) 0x25) = 0;

```
delay(1000); // Wait for 1000 millisecond(s)
```

So how do we write 32 to 0x25 (PORTB)?

\* ( (volatile byte\*) 0x25) = 32; //replaces two lines of the above code delay(2000); // Wait for 1000 millisecond(s)

```
* ( (volatile byte*) 0x25) = 0;
```

}

delay(1000); // Wait for 1000 millisecond(s)

This is good. We can make it better by using the #define

### #define blink13 \* ( (volatile byte\*) 0x25)

```
void setup()
```

```
DDRB = 32;
```

```
void loop()
```

```
blink13 = 32; // replaces * ( (volatile byte*) 0x25) = 32;
delay(2000); // Wait for 1000 millisecond(s)
blink13 = 0; // ( (volatile byte*) 0x25) = 0;
delay(1000); // Wait for 1000 millisecond(s)
}
```

#define allows us to create blink13 - sorta like a variable

#### #define blink13 <u>\* ( (volatile byte\*) 0x25)</u> #define blink13Set \* ( (volatile byte\*) 0x24)

```
void setup()
```

```
blink13Set = 32; // replaces DDRB = 32;
}
```

void loop()

}

```
blink13 = 32; // replaces * ( (volatile byte*) 0x25) = 32;
delay(2000); // Wait for 1000 millisecond(s)
blink13 = 0; // ( (volatile byte*) 0x25) = 0;
delay(1000); // Wait for 1000 millisecond(s)
```

### 14.4.2 PORTB - The Port E

Bit	7
0x05 (0x25)	PORTB7
Read/Write	R/W
Initial Value	0

14.4.3 DDRB - The Port B



14.4.4 PINB - The Port B Ir

We replace DDRB with blink13Set assigning 0x24 DDRB memory location

# We have been using axee, time for a scalpel

0	0	1	0	0	0	0	0

Ok, Pin 13 is turned on, but the other pins are turned off!

## BARE METAL PROGRAMMING - QUICK REGISTER REMINDER

Port B has an 8 Bit Register

PortB<mark>0</mark> Digital Pin 8

PortB<mark>1</mark> Digital Pin 9

PortB<sup>2</sup> Digital Pin 10

PortB<mark>3</mark> Digital Pin 11

PortB<mark>4</mark> Digital Pin 12

PortB Digital Pin 13 (LED\_BUILTIN);

We cannot access PortB<mark>6</mark> or PORTB

We want to turn on Pin13

Therefore all the ports are set to Zero except for PortB5

00100000 binary

00320000 = 0+0+32+0+0+0+0

Port	Bin	Dec
B0	0	0
B1	0	0
B2	0	0
B3	0	0
B4	0	0
<mark>B5</mark>	1	<mark>32</mark>
B6	0	0
B7	0	0

We have been using axe, time for a scalpel

0	0	1	0	0	0	0	0

Ok, Pin 13 is turned on, but the other pins are turned off!

This is not very efficient. We just to turn on PB5 or Pin13

First we need to get to the truth. The above is a Logic Truth Table and Not Truth Table

OR, AND, XOR - TRUTH TABLES

NOT ~ TRUTH TABLE

Α	В	OR	AND &	XOR ^
False	False	False	False	False
False	True	True	False	True
True	False	True	False	True
True	True	True	True	False



### We have been using axe, time for a scalpel

### We have been using axe, time for a scalpel OR OPERATION - TURN ON A PIN

0	0	0	0	1	0	1	0
0	0	1	0	0	0	0	0

OR

0	0	1	0	1	0	1	0
---	---	---	---	---	---	---	---

PORTB = PORTB|32 OR PORTB|=32 - turns on Pin 13 while leaving on Pin 9 and Pin 11

We have been using axe, time for a scalpel AND OPERATION - TURN OFF A PIN

	0	0	1	0	1	0	1	0
AND	1	1	0	1	1	1	1	1

0	0	0	0	1	0	1	0
---	---	---	---	---	---	---	---

PORTB = PORTB&223 OR PORTB&=233 - turns off Pin 13 while leaving on Pin 9 and Pin 11

### We have been using axe, time for a scalpel AND OPERATION - TURN OFF A PIN

PORTB = PORTB&223 OR PORTB&=233 - turns off Pin 13 while leaving on Pin 9 and Pin 11

233 Really? How am I am going to remember that?

### We have been using axe, time for a scalpel AND OPERATION - TURN OFF A PIN

PORTB = PORTB&223 OR PORTB&=233 - turns off Pin 13 while leaving on Pin 9 and Pin 11

233 Really? How am I am going to remember that?

Bit Shifting to the rescue!

### Bit Shifting

0	0	1	1	1	0	1	0	PORTB
0	1	1	1	0	1	0	0	PORTB <<1
1	1	1	0	1	0	0	0	PORTB <<2
1	1	0	1	0	0	0	0	PORTB <<3

### Bit Shifting

0	0	0	0	0	0	0	1	PORTB
0	0	0	0	0	0	1	0	PORTB <<1
0	0	0	0	0	1	0	0	PORTB <<2
0	0	0	0	1	0	0	0	PORTB <<3

We have been using axe, time for a scalpel

Bit Banging - one bit on

<b>AD</b>	0	0	0	0	1	0	1	0	
OR	0	0	1	0	0	0	0	0	1<<5
	0	0	1	0	1	0	1	0	

**PORTB** | = 32 **PORTB** |=(1<<5)

### Bit Shifting

0	0	0	0	0	0	1	0	1<<2
1	1	1	1	1	1	0	1	~(1<<2)

### **Bit Shifting**



**PORTB &= 223 PORTB &=~(1<<5)** 

We have been using axe, time for a scalpel

Bit Banging - one bit on

1	0	1	0	1	0	1	0	1	0	0	0	1	0	1	0
1	1	1	1	1	1	1	0	1	1	1	1	1	1	1	0
1	0	0	0	1	0	1	0	1	0	1	0	1	0	1	0

XORR

XORR

PORTB ^ (1<<5) or PORTB ^= (1<<5)
XOR one or other but not both</pre>

### Turn bits on and off

Commit this to memory. You will see it everywhere

Turn PB5 **on**: Turn PB5 **off**: **Toggle** PB5:

PORTB |= (1 << 5) PORTB &= ~(1 << 5) PORTB ^= (1 << 5)

## BARE METAL PROGRAMMING - PUTTING IT ALL TOGETHER

```
#define blink13 * ( (volatile byte*) 0x25)
#define blink13Set * ( (volatile byte*) 0x24)
void setup()
blink13Set |=(1<<5) // replaces 32 or B0010000
void loop()
  blink13 = (1<<5); // replaces 32 or B001000032; // replaces 32
  delay(2000); // Wait for 2000 millisecond(s)
  blink13 &= ~(1<<5); //
  delay(500); // Wait for 500 millisecond(s)
```